

Time-Frame Folding: Back to the Sequentiality

ICCAD 05.11.2019

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Outline

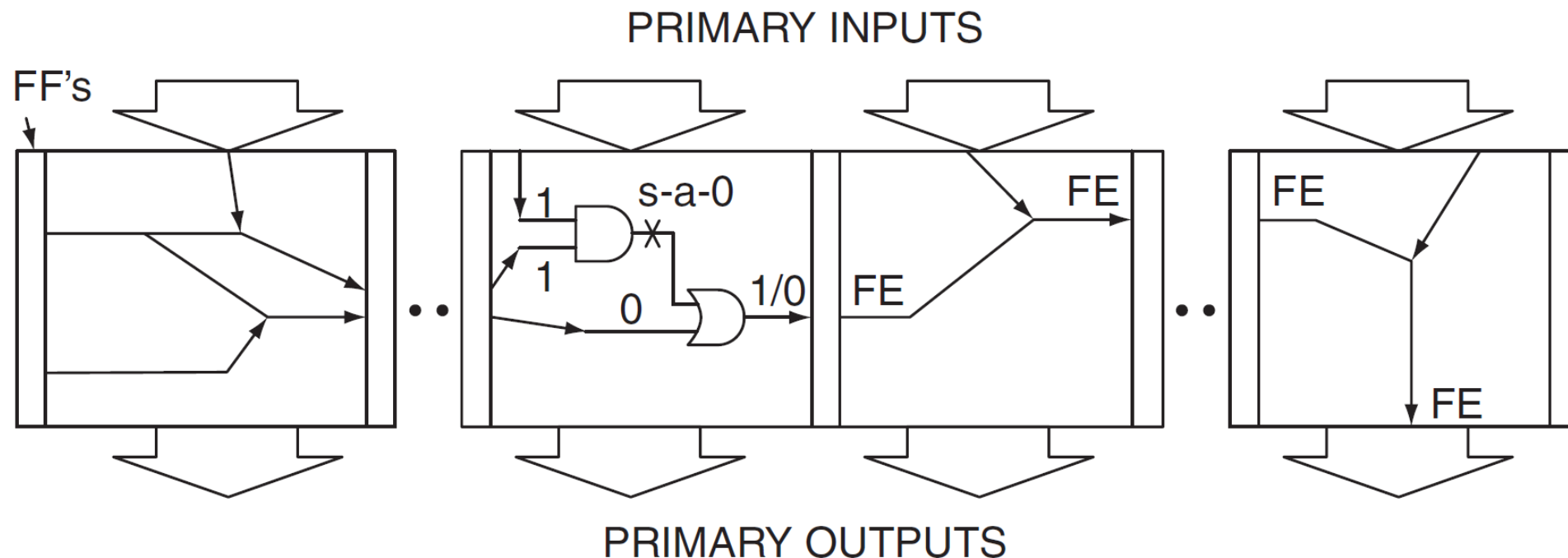
- Introduction
 - Time-Frame Unfolding vs. Folding
- Algorithm
 - State Identification
 - Transition Reconstruction
- Experiments
 - Setup
 - Results & Discussion
- Conclusions



INTRODUCTION

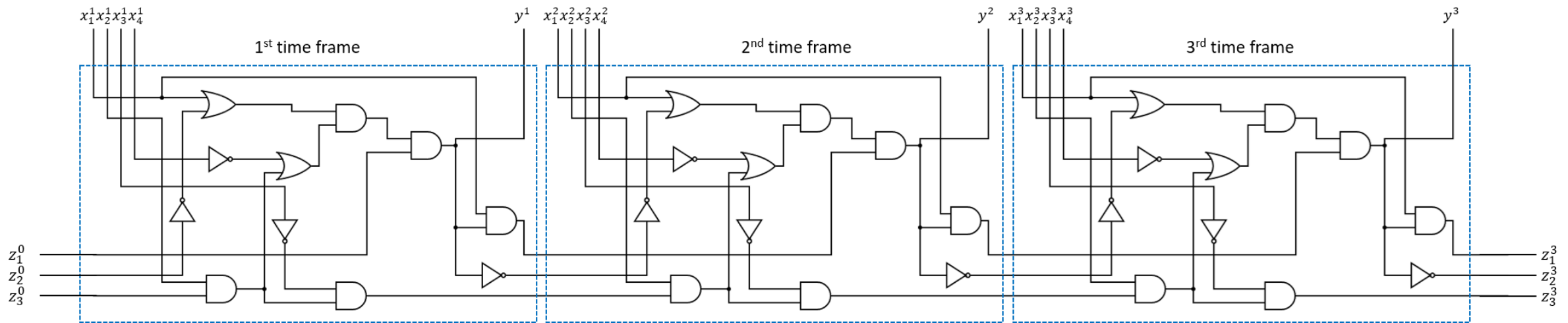
Time-Frame Unfolding

- TFU, or time-frame expansion
- A technique often used in ATPG, BMC



Time-Frame Unfolding

Expand 3 time-frames

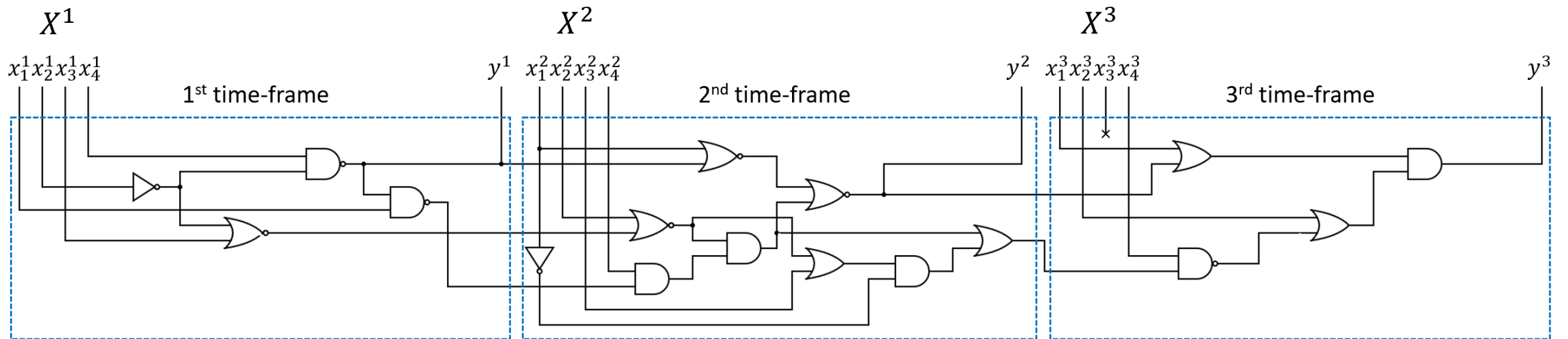


Regular duplication

with flip-flops from consecutive time-frames connected

Time-Frame Unfolding

Expand 3 time-frames



with initial state propagation and simplification

$$y^1 = f(X^1)$$

$$y^2 = g(X^1, X^2)$$

$$y^3 = h(X^1, X^2, X^3)$$

Can we reverse it?

Iterative form

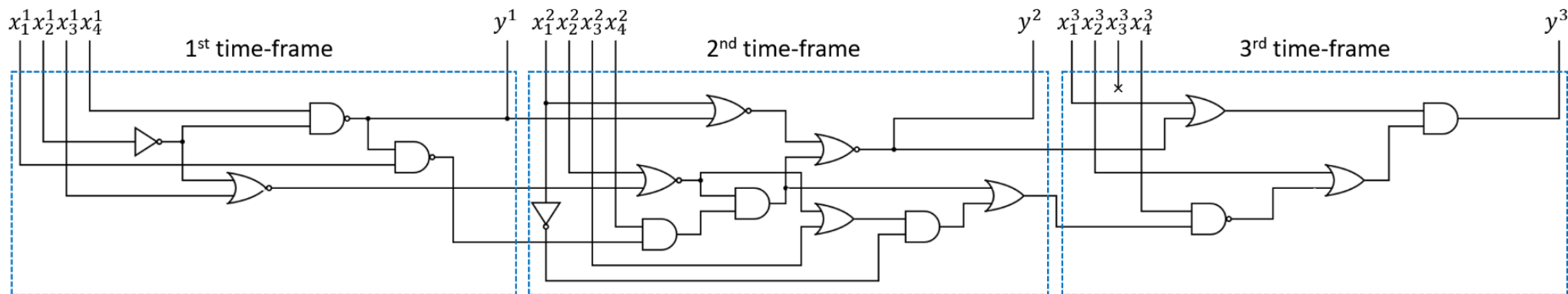
Motivation

- In model-based testing of software systems [1, 2], one may be asked to compute synchronizing, distinguishing, or homing sequences.
- These problems can be formulated as quantified Boolean formula (QBF) [3, 4] solving of strategy derivation.
- The derived strategy corresponds to **a large (iterative) combinational circuit**. However, it can be alternatively represented **more compactly by a sequential circuit**.
- How can one reconstruct a sequential circuit from an iterative combinational circuit?

Time-Frame Folding

□ TFF is a reverse operation of TFU

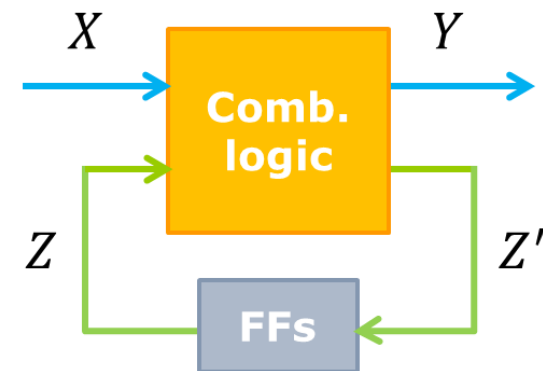
Given: a k-iterative combinational circuit



Goal: obtain a sequential circuit that

- is equivalent within bounded k time-frames
- has minimized state transition graph (STG)

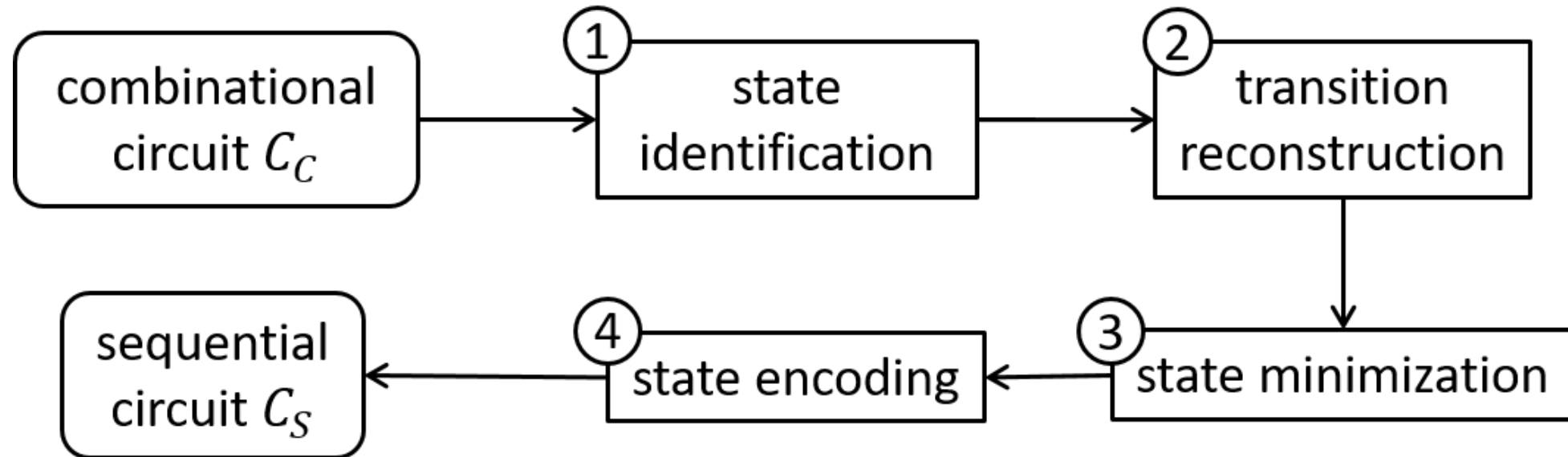
(no assumption is made on the circuit structure except for the iterative form)





ALGORITHM

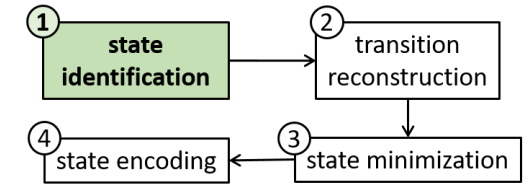
Computation Flow



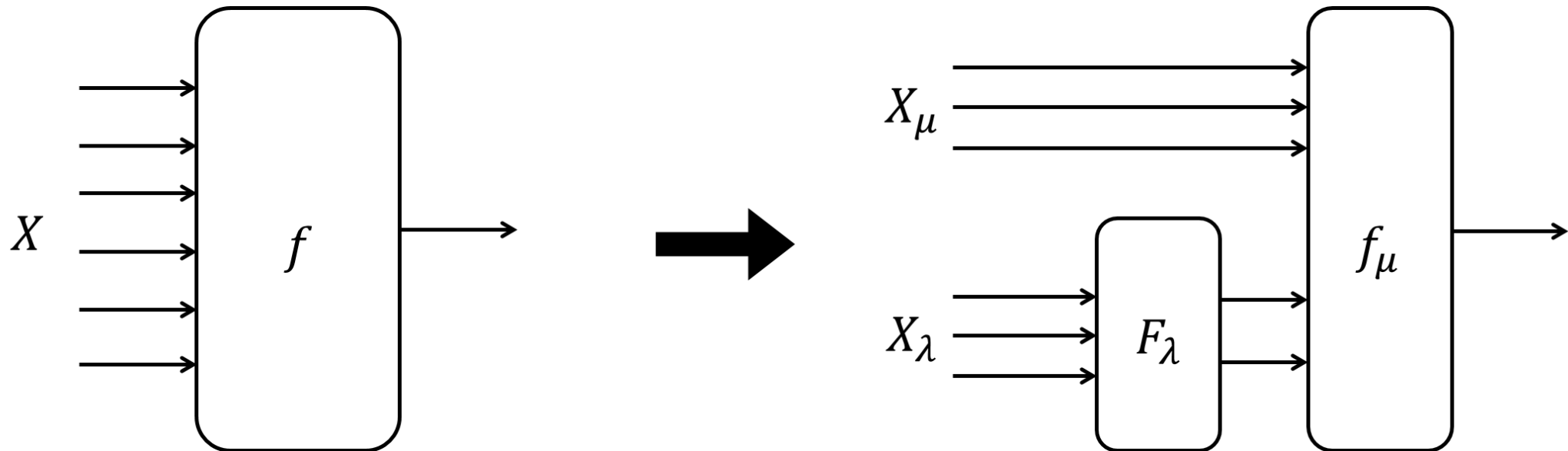
Notations

- $X^t = \{x_1^t, x_2^t, \dots, x_n^t\}$
 - X^t : the set of inputs at t^{th} time-frame
 - x_i^t : the i^{th} input at t^{th} time-frame
- $Y^t = \{y_1^t, y_2^t, \dots, y_m^t\}$
 - Y^t : the set of outputs at t^{th} time-frame
 - y_1^t : the i^{th} output at t^{th} time-frame
- $S^t = \left\{ \left(q_1^t, \tau_{q_1^t} \right), \left(q_2^t, \tau_{q_2^t} \right), \dots, \left(q_k^t, \tau_{q_k^t} \right) \right\}$
 - S^t : the set of states at t^{th} time-frame
 - q_i^t : the symbol of the i^{th} state at t^{th} time-frame
 - $\tau_{q_i^t}$: transition condition of q_i^t

State Identification

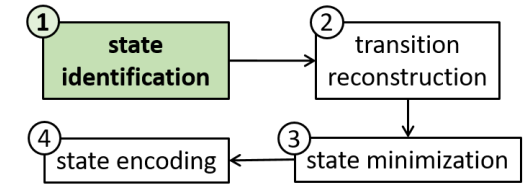


□ Functional decomposition [5, 6]



X_λ : bound set, X_μ : free set

State Identification



□ BDD-based decomposition

Decomposition chart

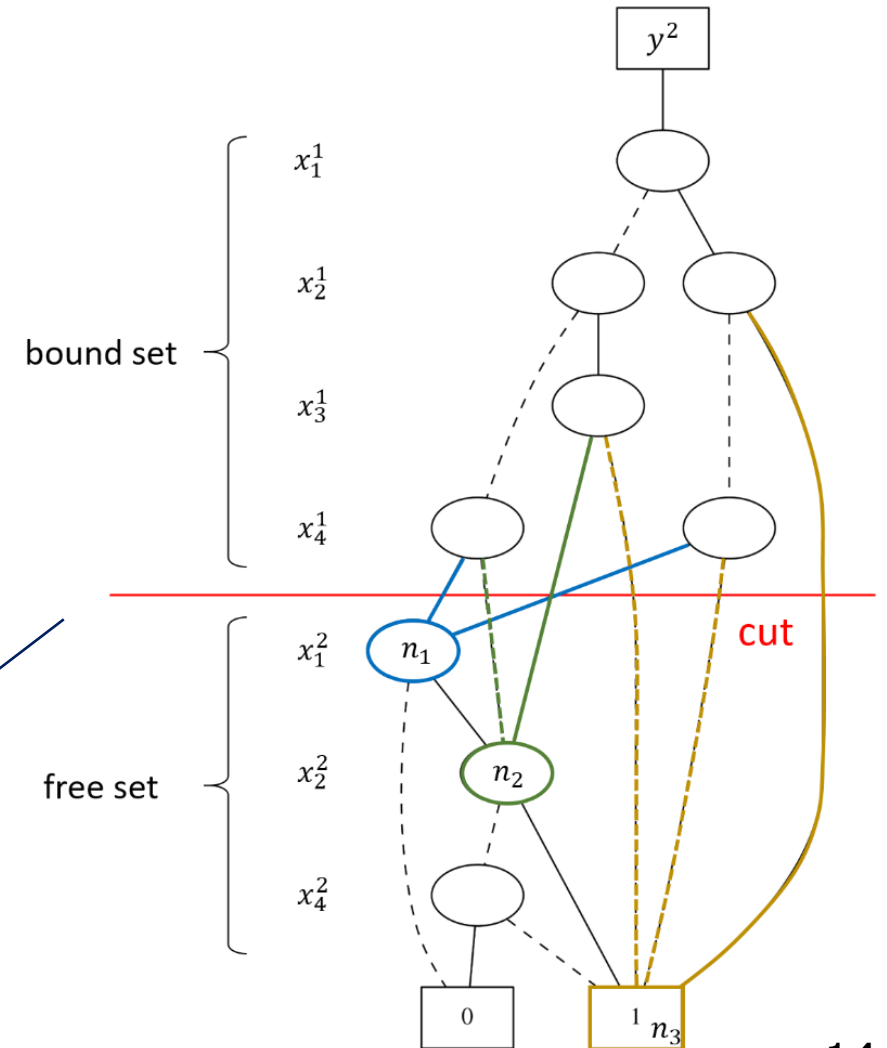
| free $x_1^2 x_2^2 x_3^2 x_4^2$ | bound $x_1^1 x_2^1 x_3^1 x_4^1$ | | | |
|-----------------------------------|------------------------------------|---|-----|-------|
| 0000 | -0-1 | 0 | 1 1 | 1 1 1 |
| 0001 | 011- | 0 | 0 0 | 1 1 1 |
| 0010 | 00-0 | 0 | 1 1 | 1 1 1 |
| 0011 | 11-- | 0 | 0 0 | 1 1 1 |
| ⋮ | 10-0 | ⋮ | ⋮ | ⋮ |
| | 010- | | | |

column patterns

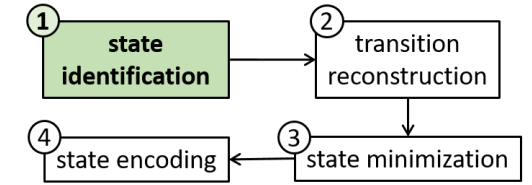
3 equivalence classes

$$\{ \overline{x_2^1 x_4^1}, \overline{x_1^1} (x_2^1 x_3^1 + \overline{x_2^1} \overline{x_4^1}), \overline{x_1^1} (x_2^1 + x_4^1) + x_1^1 x_2^1 x_3^1 \}$$

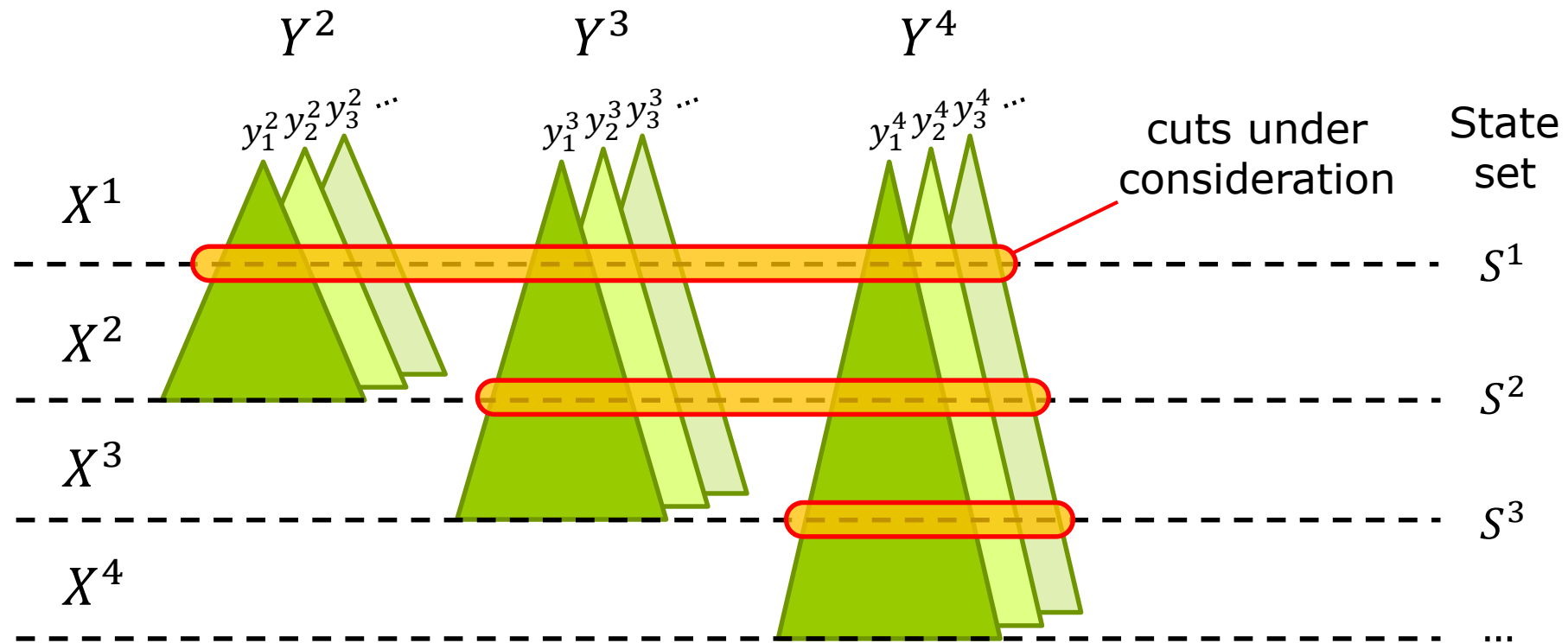
forming a partition on $\mathbb{B}^{|X^1|}$



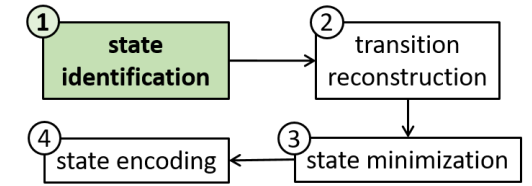
State Identification



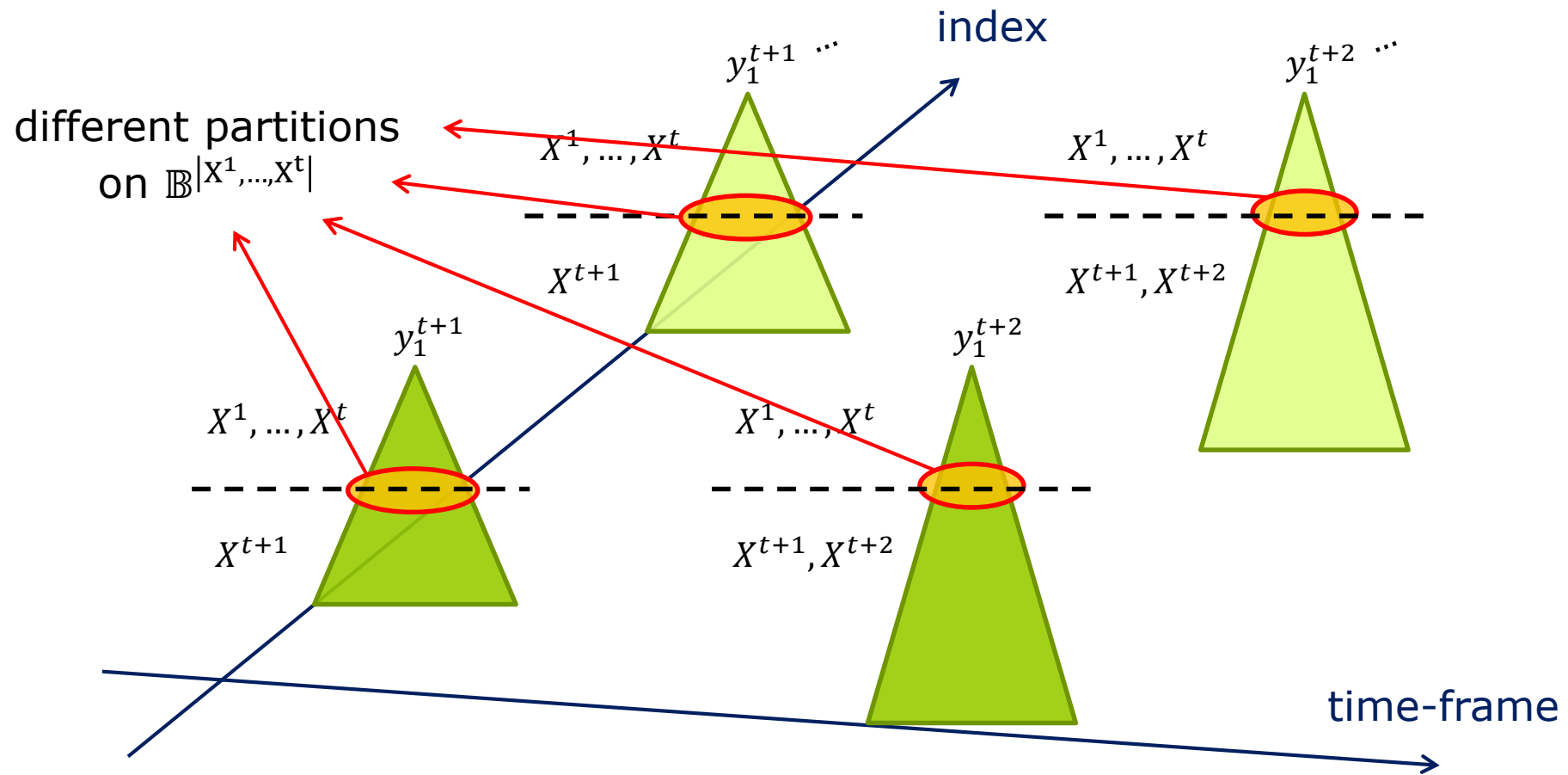
- State set S^t reached at t^{th} time-frame is determined by $\gamma^{t+1}, \gamma^{t+2}, \dots, \gamma^T$



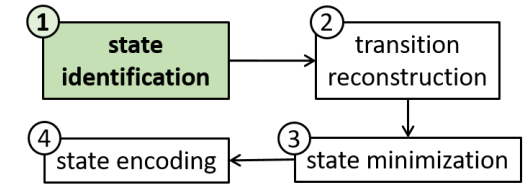
State Identification



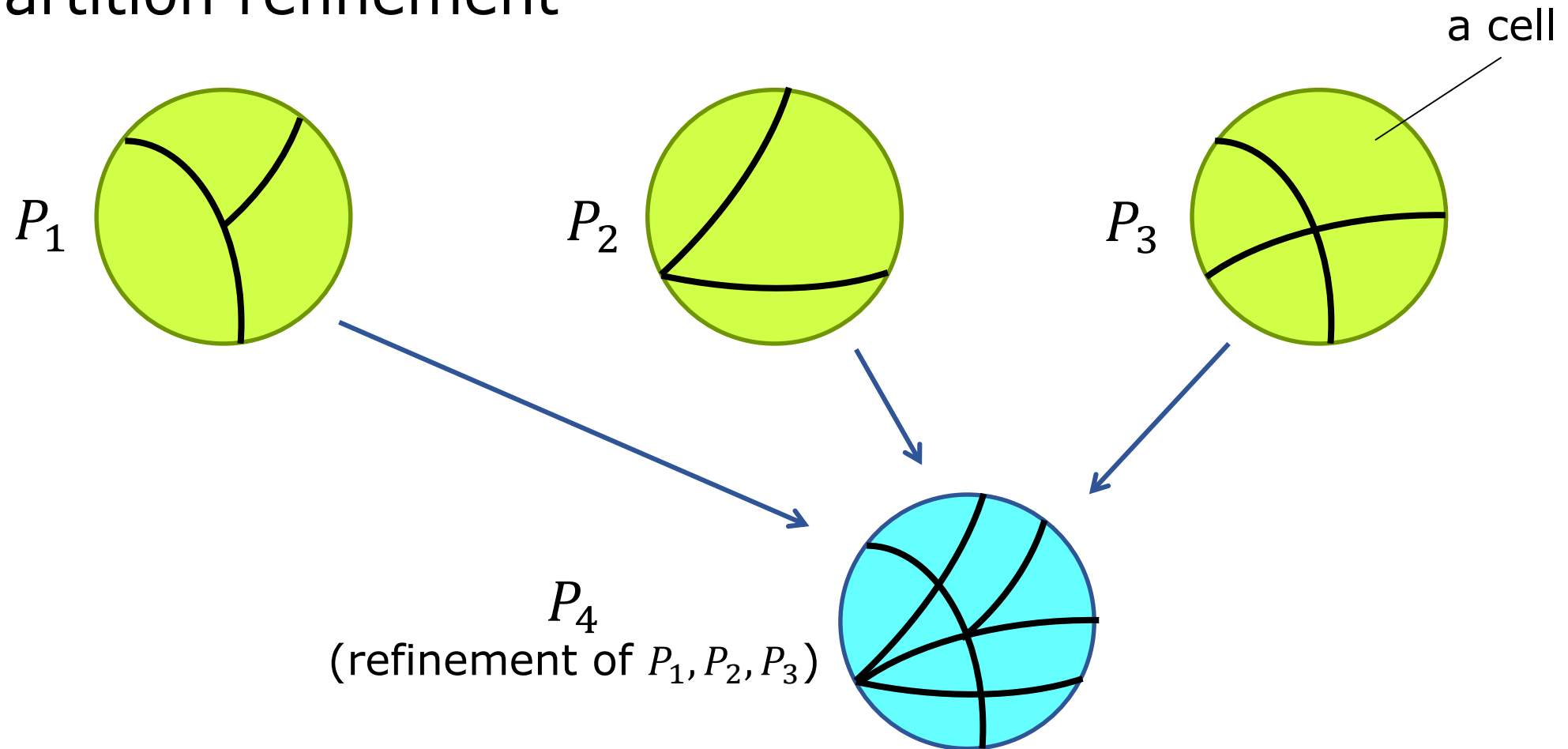
□ s^t derivation



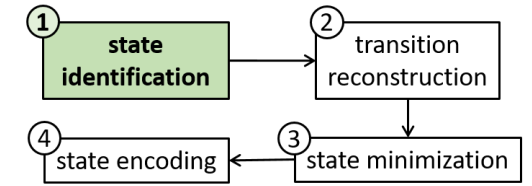
State Identification



□ Partition refinement



State Identification



- Hyper-function encoding [7]:
E.g. for a multi-output function

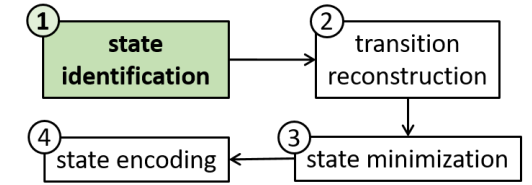
$$F(X) = \{f_1(X), f_2(X), f_3(X), f_4(X)\}$$

introduce $A = \{\alpha_1, \alpha_2\}$ to encode F into

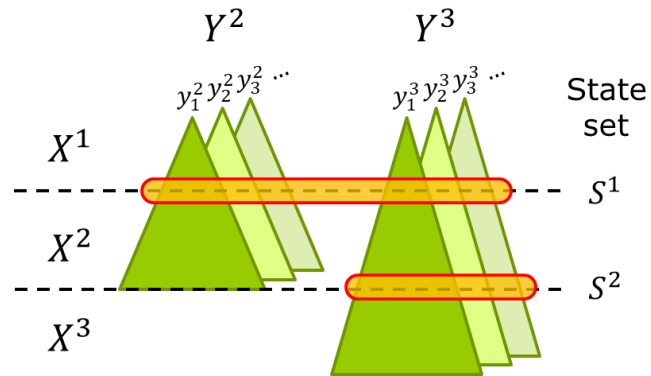
$$h(X, A) = \overline{\alpha_1} \overline{\alpha_2} f_1 + \overline{\alpha_1} \alpha_2 f_2 + \alpha_1 \overline{\alpha_2} f_3 + \alpha_1 \alpha_2 f_4$$

single-output functional decomposition algorithm can be applied

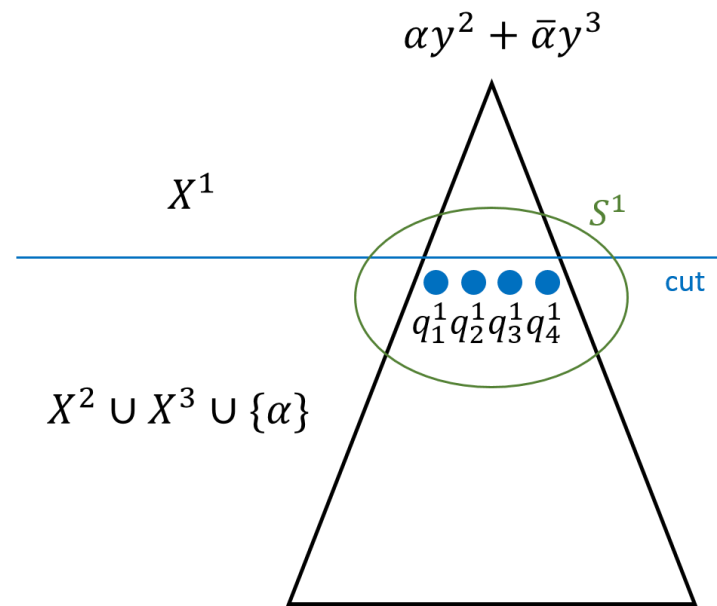
State Identification



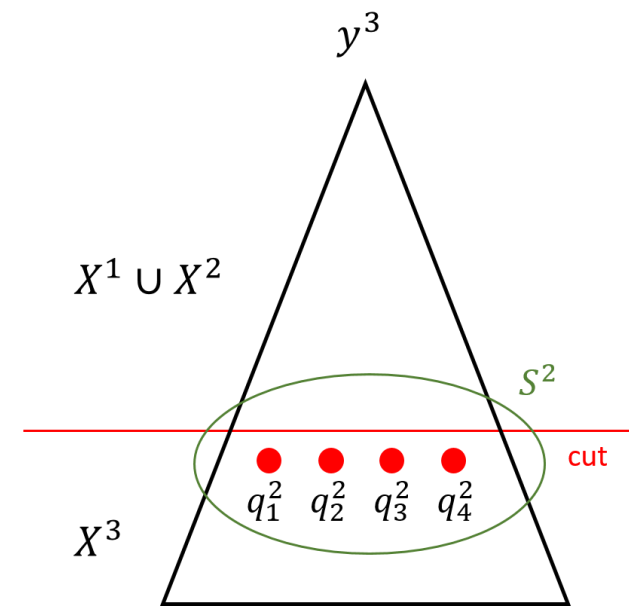
□ s27 example revisited



Hyper-functions

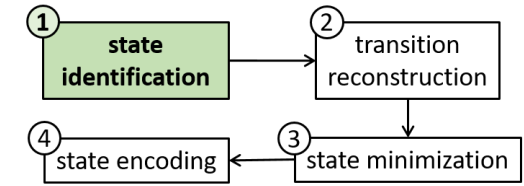


S^1 derivation



S^2 derivation

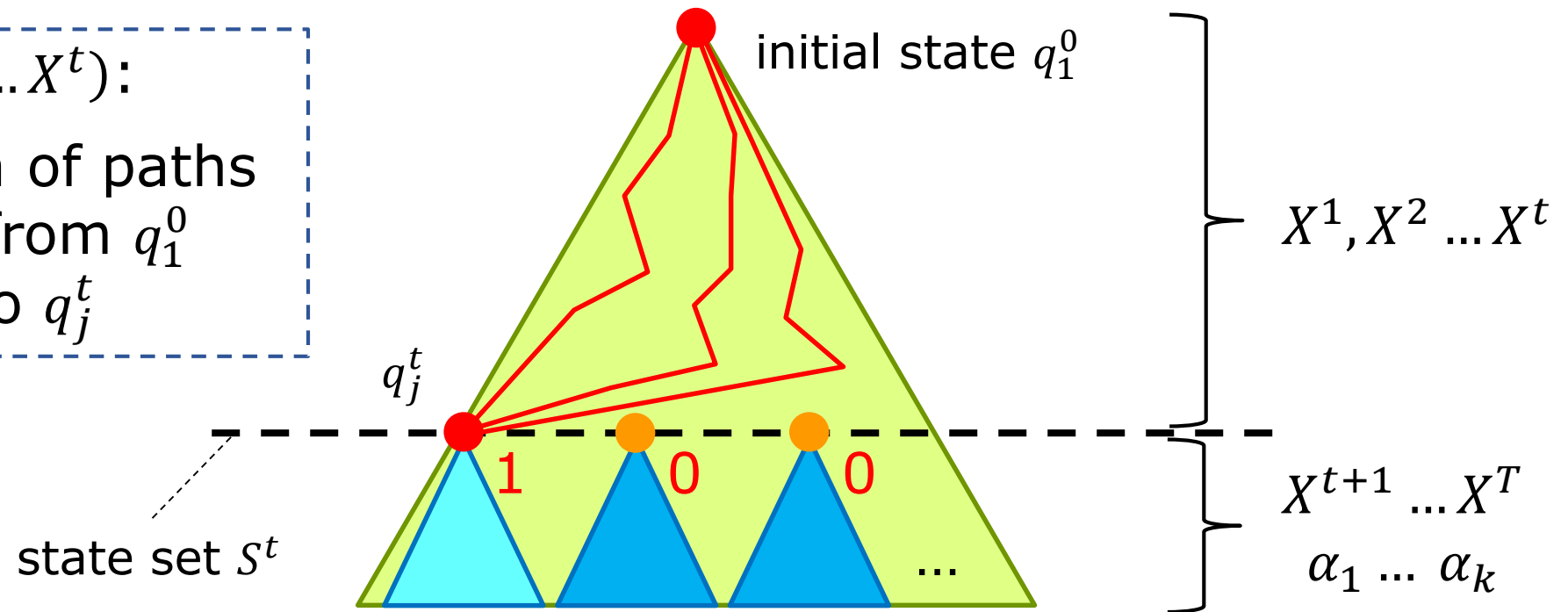
State Identification



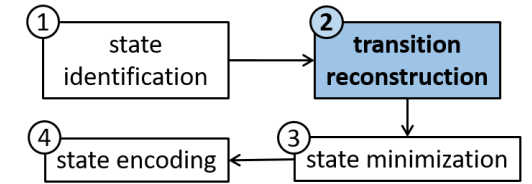
- Transition condition $\tau_{q_j^t}$ of state q_j^t

hyper-function of $\{Y^{t+1}, \dots, Y^T\}$

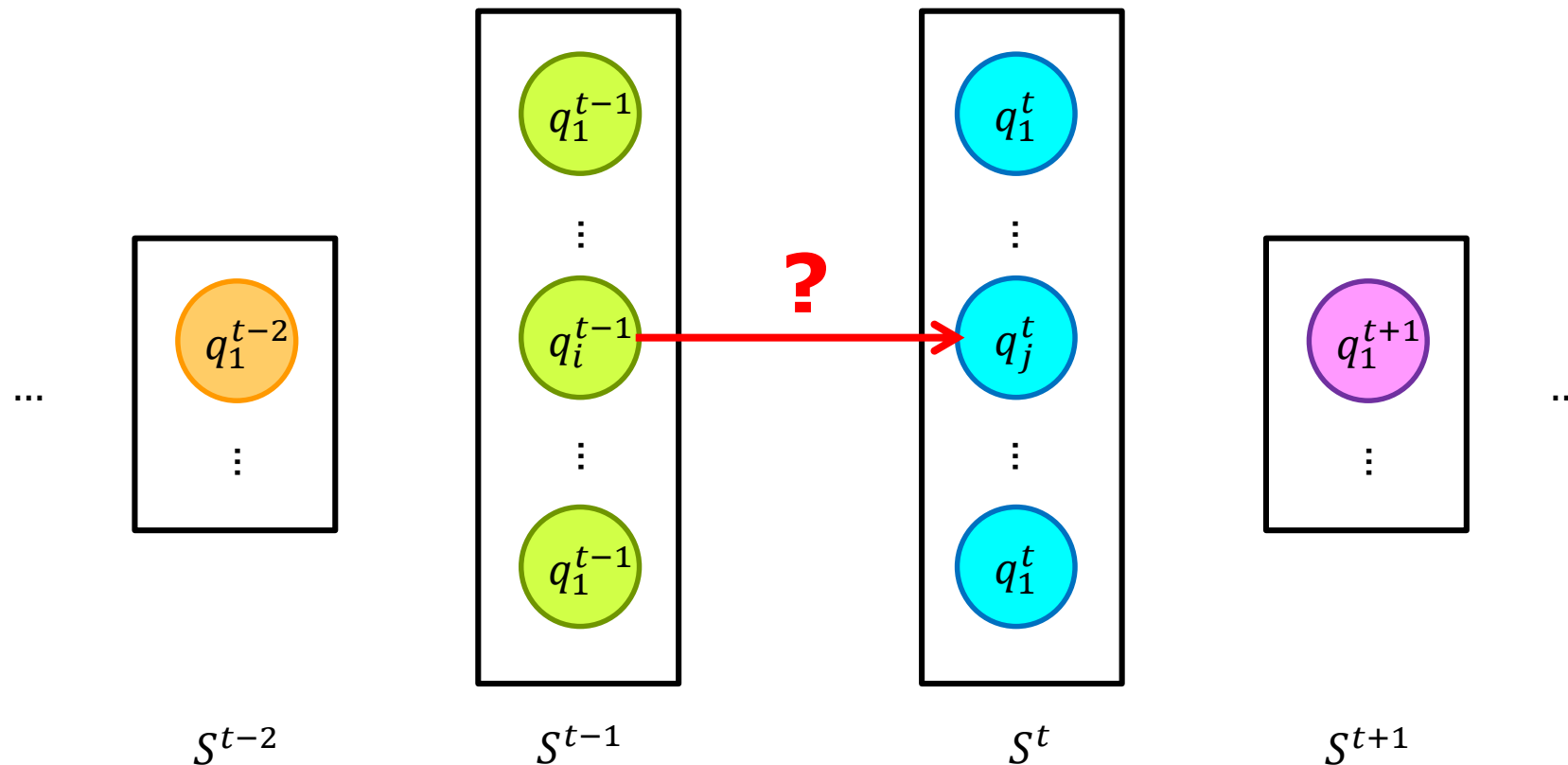
$\tau_{q_j^t}(X^1, X^2 \dots X^t)$:
collection of paths
starting from q_1^0
leading to q_j^t



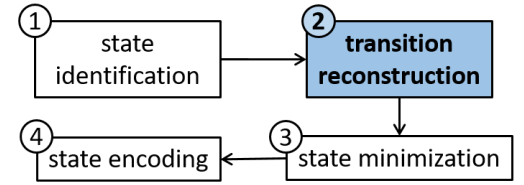
Transition Reconstruction



- Find the transition between state pairs



Transition Reconstruction



- For each pair of state (q_i^{t-1}, q_j^t) in adjacent 2 time-frames:
 - Input transition condition:

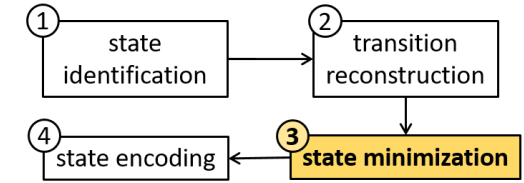
$$\varphi_{i,j}^t = \exists X^1, \dots, X^{t-1}. \tau_{q_i^{t-1}} \wedge \tau_{q_j^t}$$

global \rightarrow local info. paths to q_j^t through q_i^{t-1}

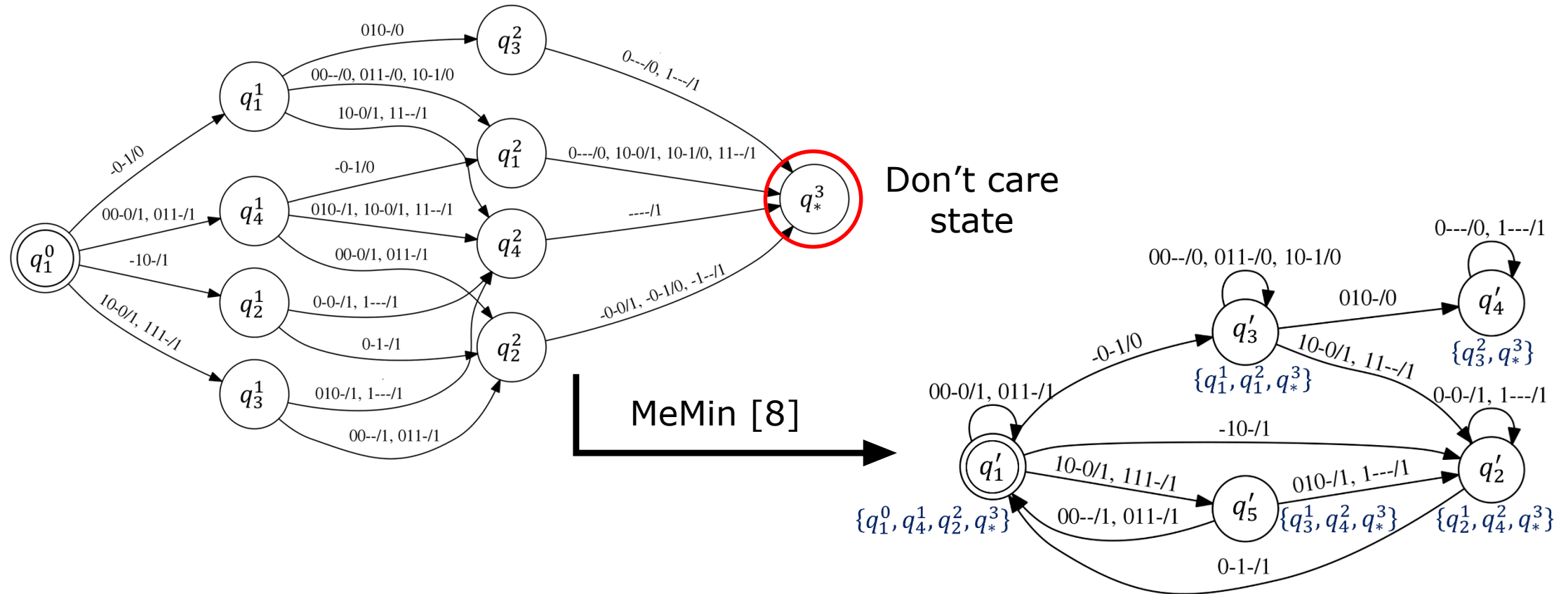
- Output transition response

$$\psi_{i,k}^t = \exists X^1, \dots, X^{t-1}. \tau_{q_i^t} \wedge y_k^t$$

State Minimization

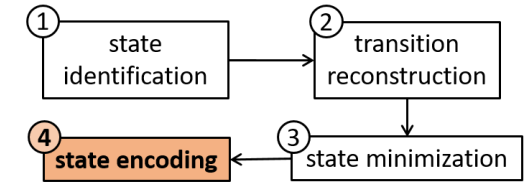


□ s27 example revisited



[8] Abel et al., 2015.

State Encoding



- Encode each state in the state set Q with actual bits, 2 schemes are applied:
 - Natural Encoding with $\lceil \log(|Q|) \rceil$ bits
 - One-hot encoding with $|Q|$ bits, each of which represents a state in Q .



EXPERIMENTS

Setup

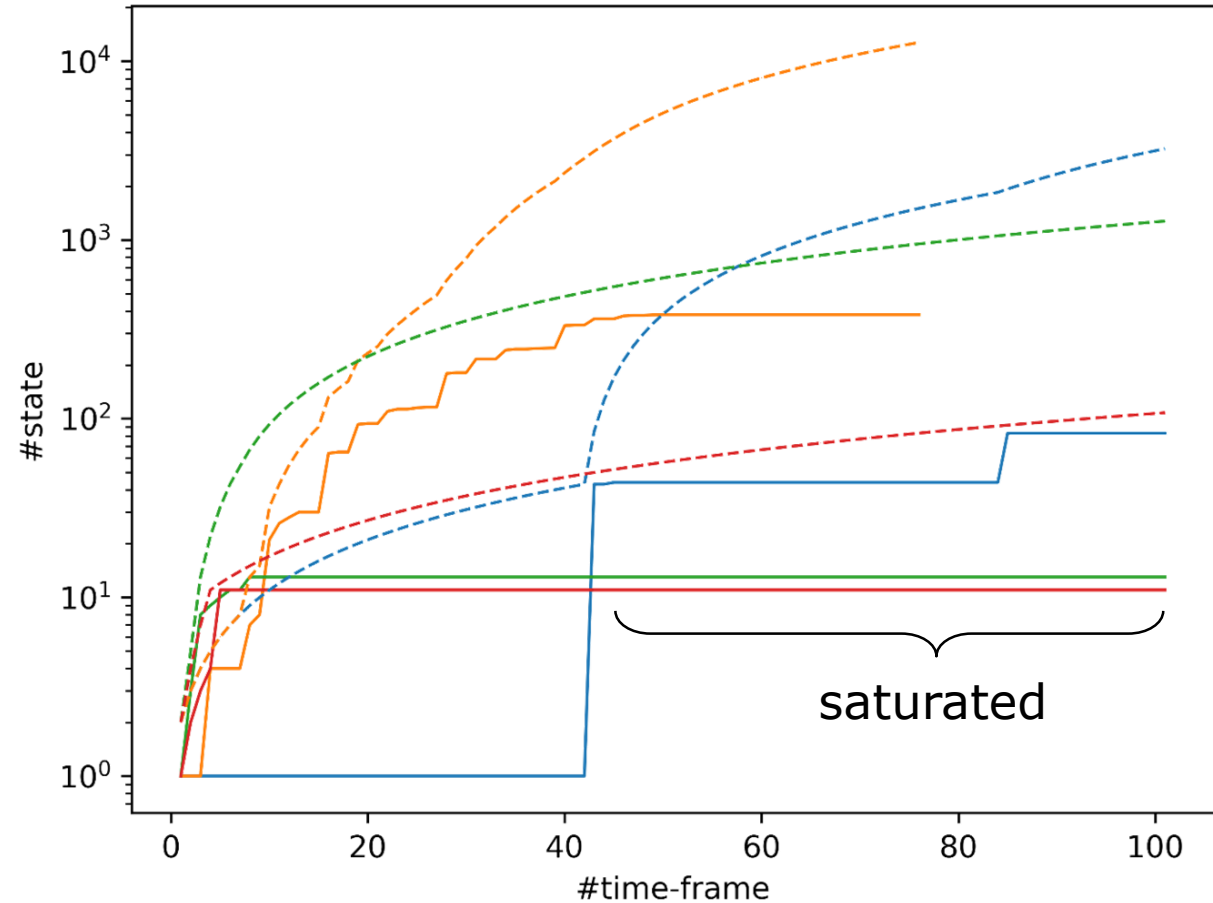
- Implemented in C++ within ABC [9] and used CUDD [10] as the underlying BDD package.
- Environment: Intel(R) Xeon(R) CPU E5-2620 v4 of 2.10 GHz and 126 GB RAM
- Benchmark circuits
 - Unfolded ISCAS/ITC circuits
 - QBF solving of homing sequence [4]
- 300s timeout limit

Results

□ Number of states

- b07
- b18
- s386
- s15850

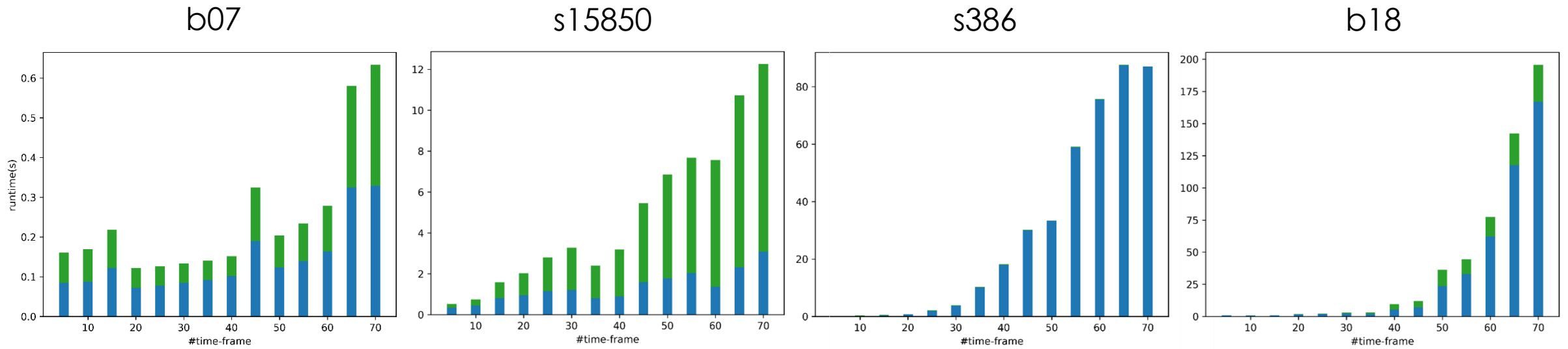
----- : #state **before** minimization
——— : #state **after** minimization



#state vs. #time-frame.

Results

□ Total runtime



runtime vs. #time-frame.

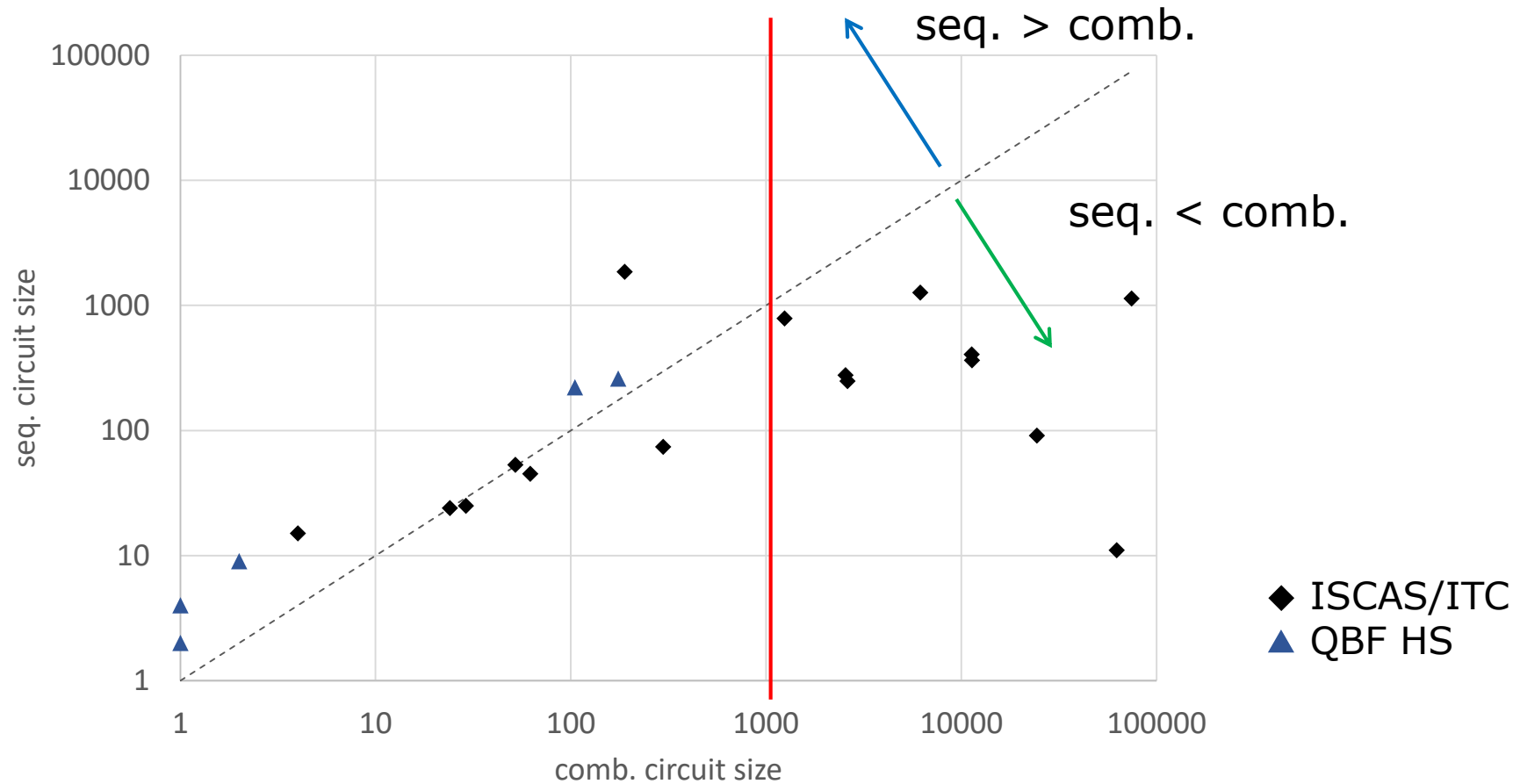


Results

| circuit | #time-frame | | expanded circuit #gate | natural encoding | | one-hot encoding | |
|---------|----------------|-------------|---------------------------|------------------|-------|------------------|-------|
| | state saturate | fixed point | | #FF | #gate | #FF | #gate |
| b01 | 9 | 9 | 52 | 5 | 109 | 18 | 53 |
| b02 | 6 | 10 | 4 | 3 | 16 | 8 | 15 |
| b03 | 14 | 14 | 189 | 10 | 8947 | 631 | 1848 |
| b05 | 69 | 133 | 62635 | 7 | 52 | 69 | 11 |
| b06 | 6 | 7 | 62 | 4 | 82 | 13 | 45 |
| b07 | 85 | 85 | 24438 | 7 | 91 | 83 | 94 |
| b08 | 55 | 55 | 6173 | 10 | 3395 | 798 | 1265 |
| b18 | 50 | 50 | 74461 | 9 | 2516 | 382 | 1134 |
| s27 | 3 | 5 | 29 | 3 | 25 | 5 | 42 |
| s298 | 20 | 23 | 1243 | 8 | 1489 | 135 | 785 |
| s386 | 8 | 9 | 297 | 4 | 124 | 13 | 74 |
| s820 | 12 | 13 | 2558 | 5 | 276 | 24 | 8639 |
| s832 | 12 | 13 | 2612 | 5 | 248 | 24 | 10075 |
| s1488 | 23 | 23 | 11298 | 6 | 578 | 48 | 406 |
| s1494 | 23 | 23 | 11367 | 6 | 526 | 48 | 364 |
| s15850 | 5 | 5 | 24 | 4 | 28 | 11 | 24 |

Results on folding with “fixed points” reached.

Results



Circuit size comparison.

Conclusions

- We have formulated the time-frame folding problem, and provided a computational solution based on functional decomposition.
- Our method guarantees the folded sequential circuit is state minimized.
- Experimental results demonstrated the benefit of our method in circuit compaction from an iterative combinational circuit to its sequential counterpart.
- Our method can be useful in testbench generation, sequential synthesis of bounded strategies, and other applications.



THE END